Complex Analysis

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Transformation or Mapping

• The equations-

u = u(x,y)v = v(x,y)(1)

define a *transformation* or *mapping* by means of which a correspondence between *uv*-plane and *xy*-plane can be established. If corresponding to each point of *xy*- plane, there is a unique point of uv-plane and conversely, then such *transformation* is called *one-one transformation*. The corresponding points in the two planes are called *images* of each other. Hence, by means of equations (1), a region or curve of *xy*-plane is said to *transform* or *mapped on* or represented by the corresponding curve of the *uv*-plane.

Conformal Transformation

Suppose the *transformation* u = u(x,y), v = (x,y) maps the two curves C₁, C₂ [intersecting at the point P(z₀)] of z-plane on the two curves C₁', C₂' [intersecting at P'(z₀)] of w-plane.

If the angle between C_1 and C_2 at z_0 is equal to the angle between C_1' and C_2' at w_0 , then the transformation is called *isogonal*. If the sense of rotation as well as the magnitude of the angle is preserved, the transformation is called *conformal*.

Let $w = \overline{z}$ is isogonal transformation.

Conformal Trasformation



Isogonal Transformation





Some General Transformations

We study the following general transformations which are used in conformal transformations –

- (1) Translation
- (2) Rotation
- (3) Magnification
- (4) Inversion

Now we describe these with suitable examples.

(1) <u>Translation</u> – The map $w = z+\beta$ corresponds to a translation. For, by this transformation, the figure in w-plane is the same as the figure in z- plane with a different origin.

Example -

Let a rectangular domain R be bounded by x=0, y=0, x=2, y=1. Determine the region R' of w-plane into which R is mapped under the transformation

w = z+(1-2i)This gives u=1, u=3 as x=0, x=2 and v=-2, v=-1 as y=0, y=1 respectively. Hence the required image is rectangle R' bounded by u=1, u=3, v=-2, v=-1 in w-plane as shown in the figure.



(2) Rotation-

By the transformation $w = z e^{i^{\theta_0}}$,

figures in z-plane are rotated through an angle ${}^{\theta}_{0}$. If ${}^{\theta}_{0} > 0$, the rotation is anti-clockwise and ${}^{\theta}_{0} < 0$, the rotation is clockwise.

Example-

Consider the transformation $w = z e^{i\pi/4}$ and determine the region R' in w-plane corresponding to the triangular region R bounded by the lines x= 0, y= 0, and x+y= 1 in z-plane.

This gives v = -u, v = u when we put x = 0, y = 0 respectively and at x+y=1, $v = 1/\sqrt{2}$.

The two regions are shown in the following figure. The mapping w = z $e^{i\pi/4}$ performs a rotation of R through an angle $\pi/4$.





(3) Magnification (Stretching)-

Consider the map w = az, where a is real. The two figure in z-plane and w-plane are similar and similarly situated about their respective origin, but the figure in w-plane is a times the figure in z-plane.

Such map is called magnification or stretching or dilation.

Example-

Consider the transformation w = 2z, and determine the region R' of w-plane into which the triangular region R enclosed by the lines x=0, y=0, x+y=1 in the z-plane is mapped under the map. Which gives us u = 0, v = 0 at x = 0, y = 0 respectively, and u+v = 2 at x+y = 1.

This transformation w = 2z performs a magnification of R into R'.





(4) Inversion-

By means of the transformation w = 1/z, figure in z-plane are mapped upon the reciprocal figures in w-plane.

Example –

Consider the map w = 1/z and determine the region R' in w-plane of the infinite strip R bounded by 1/4 < y < 1/2. Finally

 $1/4 < y < 1/2 \Rightarrow u^2 + (v + 2)^2 < 2^2$ and $u^2 + (v + 1)^2 > 1$.

This shows that region R' in w-plane is bounded by the two circles.



